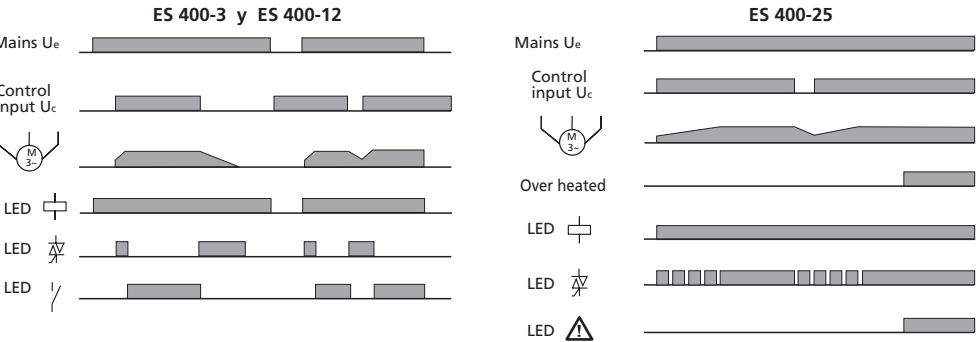
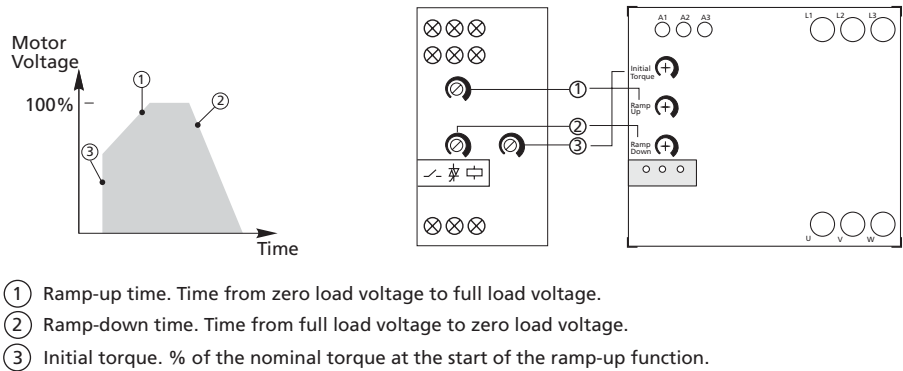
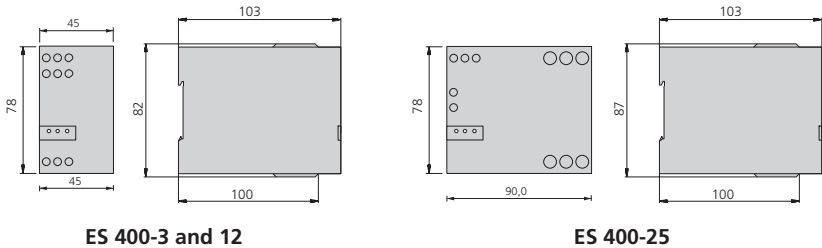


Operation Diagrams



Dimensions (mm)



Type selection (with recommended manual motor starters)

		Motor full load current (A)												
		0,1 0,16	0,16 0,25	0,25 0,4	0,4 0,63	0,63 1	1 1,6	1,16 2,5	2,5 4	4 6,3	6,3 10	10 16	16 20	20 25
FANOX Manual motors starters		M-0,16	M-0,25	M-0,4	M-0,63	M-1	M-1,6	M-2,5	M-4	M-6,3	M-10	M-16	M-20	M-25
Soft starter		ES 400-3					ES 400-12					ES 400-25		

Note: The specifications are subject to change without notice. 10/01

Soft starters

ES



- The best solution for a soft start/stop for 3 phase inductive motors up to 11kW (400V).
- Potential-free control input.
- Easy setting with 3 independent potentiometers
- Internal heatsink and bypass relay incorporated.
- Compact housing for DIN rail assembly.

-Ramp-up time  
-Ramp-down time  
-Initial torque

Mode of Operation

An electronic circuit comprising semiconductor components starts the motor without the use of contacts. Neither switching sparks nor contact erosion occur.

Only when the motor nominal voltage is reached the power semiconductor devices are bypassed by relay contacts. Thanks to this technology, the ES motor controllers are substantially longer lasting than conventional contactors.

Easy to install and control. The ES control can take place either from outside by means of a control signal, eg, a programmable controller, or directly via the power supply of the motor to be controlled.

Type selection

	Nominal current	Nominal voltage	Motor rating		Weight	Code No.
			kW	HP		
ES 400-3	3 A	400 Vac	1,1	1,5	270 gr	41803
ES 400-12	12 A	±15%	5,5	7,5	270 gr	41812
ES 400-25	25 A	(50-60 Hz)	11	15	530 gr	41825

Input Specifications (Control Input)

Control voltage U <sub>c</sub>	24 - 110 VAC/DC ±15%, 12 mA
A1-A2:	110 - 480 VAC ±15%, 5 mA
A1-A3:	
Rated insulation voltage	630 V rms Overvoltage cat. III (IEC 664)
Dielectric strenght	
Dielectric voltage	2 kV (rms)
Rated impulse withstand volt.	4 kV (1,2/50 µs)

Output Specifications

Utilization category	CA 53b integral bypassing of semiconductors
Overload current profile (overload relay trip class)	ES 400-3: 6/13 ES 400-12: 6/13 ES 400-25: 3/4/120

Supply Specifications

Power supply Rated operational volt. (U <sub>0</sub> ) trought terminals L1-L2-L3	Overvoltage Cat. III (IEC 664) (IEC 38) 400 Vac rms ±15% 50/60 Hz -5/+5 Hz ≤40 ms 2 kV (rms) Rated impulse withstand volt. 4 kV (1,2/50 μs)
Voltage interruption Dielectric voltage Rated impulse withstand volt.	5 VA L1-L2
Rated operational power supplied from	

Semiconductor Data

Rated opera- tional current	I²t for fusing t = 1 - 10 ms	I <sub>TSM</sub>	di/dt
3 A	72 A² s	120 Ap	50 A/μs
12 A	610 A² s	350 Ap	50 A/μs
25 A	1250 A² s	500 Ap	100 A/μs

Mode of Operation

This motor controller is intended to be used to soft start/stop 3 phase squirrel cage induction motors and thereby reduce the stress or wear on gear and belt/chain drives and to give smooth operation of machines. Soft starting and/or stopping is achieved by controlling the motor voltage. During running operation the semiconductor is bypassed by an internal electromechanical relay

**Overtemperature (only ES400-25)**  
The ES 400-25 will not start if the heatsink has a temperature which is exceeding approx 100°C. When overtemperature occurs the soft starter will not ramp-up. Reset takes place when the temperature drops below the critical value and only if the supply is interrupted and reapplied.

Display Information

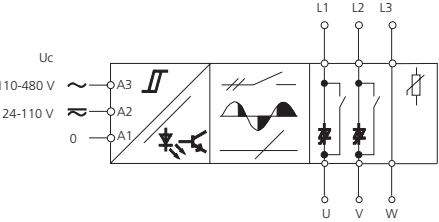
	ES400-3	ES400-12	ES400-25
Power Supply	green	green	green
Ramp	yellow	yellow	yellow (flashing)
Bypass relay on	yellow	yellow	yellow
Overtemperature			red

General Specifications

Accuracy Ramp-up	≤ 0,5 s on min. 5,5-7,5s on max. (ES400-3 and 12) 10±10% on max. (ES400-25)
Ramp-down	≤ 0,5 s on min. 6 -10s on max. (ES400-3 and 12) 20±10% on max. (ES400-25)
Initial torque	±15% on max. (ES 400-3 and 12) ±5% on max. (ES 400-25) < 5% on min.
EMC Immunity	Electromagnetic Compatibility acc. to EN 50 082-2
Environment Degree of protection Pollution degree Operating temperature Storage temperature	IP 20 3 -20 a +50°C (-4 to +122°F) -50 a +85°C (-58 to +185°F)

<b>ES 400-3 y ES-400-12</b> Control and Line screw terminals Minimum Max. tightening torque	2,5 mm² , AVG 14 0,5 mm² , AWG 20 0,6 Nm
<b>ES 400-25</b> Control screw terminals Minimum Max. tightening torque Line screw terminals	2,5 mm² , AVG 14 0,5 mm² , AWG 20 0,6 Nm 10 mm² , or 2 x 6 mm² AWG 6 or 2 x AWG 10 1 mm² , AWG 16 2 Nm
Minimum Max. tightening torque	

Functional Diagram



Settings

	ES400-3	ES400-12	ES400-25
Initial torque (% of nominal torque)	0-85%	0-85%	5-50%
Ramp-up time	0,5-5 s	0,5-5 s	0,5-10 s
Ramp-down time	0,5-5 s	0,5-5 s	0,5-20 s

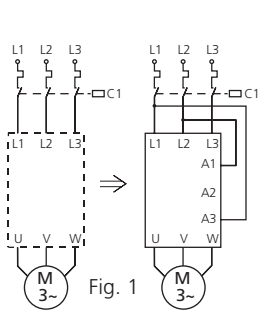
Applications

Changing from Direct ON Line start to soft start (Line controlled soft start) (Fig. 1)

Changing a Direct On Line start into a soft start is very simple with the ES soft starting relay:

- 1) Cut the cable to the motor and insert the ES relay.
- 2) Connect control input to two of the incoming lines. Set initial torque to minimum and ramp up and down to maximum.
- 3) Power up again, adjust the start torque so the motor starts turning immediately after power is applied, and adjust ramp time to the appropriate value.

When C1 is operated, the motor controller will perform soft start of the motor. When C1 is switched off, the motor will stop, the motor controller will reset and after 0.5 s a new soft-start can be performed.



Time between rampings

To prevent the semiconductors from overheating, a certain time between ramping should be allowed. The time between rampings depends on the motor current during ramping and ramp time.

ES 400-3				ES 400-12				ES 400-25					
I <sub>ramp</sub> (A)	Ramp time			I <sub>ramp</sub> (A)	Ramp time			I <sub>ramp</sub> (A)	Ramp time				
	1	2	5		1	2	5		1	2	5	7	10
18	15s	30s	15min	72	2,5min	5min	40min	150	4min	8min	20min	-	-
15	12s	20s	60s	60	1,5min	3min	13min	125	3min	6min	14min	19min	-
12	10s	20s	50s	48	50s	1,5min	5min	100	2min	4min	9min	12min	18min
9	8s	12s	30s	36	30s	1min	3min	75	1min	2min	5min	7min	10min
6	5s	9s	25s	24	15s	40s	15min	50	27s	53s	2min	3min	4min
3	2s	5s	20s	12	10s	20s	50s	25	7s	13s	33s	47s	67s
1,5	1s	2s	5s	6	5s	9s	20s						

Note: Table is valid for ambient temperature 25°C. For higher ambient temperature add 5% per°C to values in the tables. The more shaded areas in the tables are for blocked rotor. Do not repeat rampings with blocked rotor.

Fusing Considerations

The motor controller provides by-passing of the semiconductors during running operation. Therefore the semiconductors can only be damaged by short-circuit currents during ramp-up and ramp-down function.

A 3-phase induction motor with correctly installed and adjusted overload protection does not short totally between lines or directly to earth as some other types of loads, e.g. heater bands. In a failing motor there will always be some part of the winding to limit the fault current. If the motor is installed in an environment where the supply to the motor cannot be damaged, the short-circuit protection can be considered to be acceptable if the controller is protected by a 3-pole thermal-magnetic overload relay.

If the risk of short-circuit of the motor cable, the soft starter or the load exists, then the soft starter must be protected by ultrafast fuses, e.g. for a 3 A type: Ferraz 660 gRB 10-10, for an 12 A type: Ferraz 660 gRB 10-25. Fuseholder type PST 10.

